



ANCIT

SOFTWARE DEFINED VEHICLES 4 WEEKS TRAINING (160 Hrs)

Company Confidential ANCIT



Software Defined Vehicle Course Agenda from ANCIT

Delivery Format : This Course is offered in Classroom or Online Format

Duration: 160 Hours (4 Weeks)

Target Group : Automotive software engineers, embedded systems engineers, and DevOps teams

Prerequisites : Basic understanding of automotive electronics, embedded systems, Linux OS, and

AUTOSAR

Outcome : Comprehensive knowledge of SDV, AUTOSAR, and SoC technologies along with

Hands-on expertise in RTOS, Linux, Yocto, Android Automotive, and Docker containerization and the ability to implement and test OTA updates, AUTOSAR

stacks, and virtualization.

Day 1. SDV Overview

· Why SDV, its goals, and challenges in implementation

Enabling technologies and vehicle operating systems introduction

Day 2: Service-Oriented Architecture (SOA)

- · Layers and integration with functional safety
- Overview of E/E architectures and SDV tech stack
- · Introduction to Over-The-Air (OTA) architecture and updates

Day 3. System on Chip (SoC)

- Comparison of SoCs like JACINTO, S32G2XX, RCAR, and NVIDIA ORIN
- Architecture, applications, and challenges in implementation

Day 4. Virtualization Concepts

- · Evolution of vehicle architecture
- · Vehicle OS layers: base layer, middleware, infrastructure, and hardware

Day 5,6,7: FreeRTOS and QNX Implementation:

- Understanding RTOS from NXP and implementing FreeRTOS on M7 core
- Inter-processor communication and comparison of QNX with Linux

Day 8,9,. Advanced Linux OS

- Linux kernel modules, system debugging, profiling, and building Linux systems
- Flashing and running an embedded Linux system on S32G274 (A53 cores)



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Day 10,11. Yocto Project

· Building and customizing Linux OS using Yocto and flashing on S32 board

Day 12. U-Boot

- U-Boot creation, configuration, and testing commands
- · Loading files from FAT partitions and handling flash

Day 13,14. Android Automotive OS (AAOS)

- Building Android Automotive OS and customizing its Linux kernel
- · HIDL (Hardware Interface Definition Language) and VHAL (Vehicle HAL) integration

Day 15,16. Classic AUTOSAR

- · Architecture, communication stack, and Ethernet switch configuration
- DOIP (Diagnostic over IP) implementation

Day 17. SOME/IP and Adaptive AUTOSAR

• Implementing and testing SOME/IP with adaptive and classic AUTOSAR

Day 18. Data Distribution Services (DDS)

· DDS implementation and addressing challenges

Day 19. Containerization Using Docker:

• Docker installation, container management, and inter-container communication

Day 20. Over-The-Air (OTA) Updates

• Implementing OTA updates in ECU from an end-node perspective



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